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WHAT IS CLAIMED IS:

- 1. A method for obtaining an estimate of a noise-free portion of a noise-containing digital signal, comprising the steps of:
- (a) applying a set of M linear transforms to the noise-containing digital 5 signal;
 - (b) determining M initial de-noised estimates of each digital element of the digital signal;
 - (c) deriving a combination of weight factors for the M initial de-noised estimates of each digital element by formulating the combination as a linear estimation problem and solving it for the individual weight factors; and
 - (d) formulating a final de-noised estimate of each digital element based on the corresponding M initial de-noised estimates and the combination of weight factors determined in steps (b) and (c) respectively.
- 2. The method of claim 1, wherein the set of M linear transforms is applied to the digital signal as a whole or to each digital element.
 - 3. The method of claim 1, wherein, for each linear transform in the set of M linear transforms, the M initial de-noised estimates of a particular digital element are obtained by thresholding each transform coefficient that has an absolute value below a threshold and inverse transforming the non-thresholded transform coefficients.
 - 4. The method of claim 1, wherein the combination of weight factors is an optimal combination.
 - 5. The method of claim 1, wherein the combination of weight factors is derived such that a conditional mean squared error with respect to the initial de-noised estimates is minimized.

- 6. The method of claim 1, wherein the set of *M* linear transforms comprises (i) a discrete cosine transform and a predetermined number of its overcomplete shifts, (ii) a wavelet transform and a predetermined number of its overcomplete shifts, or (iii) a Fourier transform and a predetermined number of its overcomplete shifts.
- 5 7. The method of claim 1, wherein the digital signal is an image or video frame comprised of a plurality of pixels, wherein each digital element comprises one or a group of pixels.
 - 8. A method for obtaining an estimate \hat{x} of a noise-free portion x of a noise-containing signal y, comprising the steps of:
- obtaining an estimate $\hat{x}(n)$ for each element n of \hat{x} according to the following equation:

$$\hat{x}(n) = \sum_{i=1}^{M} \alpha_i(n) \hat{x}_i(n), n = 1,...,N$$

wherein weight factors $\alpha_i(n)$, i=1,...,M, n=1,...,N are optimally determined by formulating a combination thereof as a linear estimation problem; and

combining the N $\hat{x}(n)$ estimates to obtain \hat{x} .

- 9. The method of claim 8, wherein $\alpha_i(n)$ are optimally determined such that $\hat{x}(n)$ minimizes a conditional mean squared error with respect to the initial denoised estimates.
- 20 10. The method of claim 9, wherein $\alpha_i(n)$ are optimally determined based on a scaling factor that removes explicit dependence to noise variance and on a matrix that is dependent on an overcomplete transform set applied in obtaining each $\hat{x}(n)$.
 - 11. The method of claim 9, wherein $\alpha_i(n)$ are optimally determined based on a scaling factor that removes explicit dependence to noise variance and on a diagonal

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matrix that is derived from a matrix that is dependent on an overcomplete transform set applied in obtaining each $\hat{x}(n)$.

- 12. The method of claim 9, $\alpha_i(n)$ are optimally determined based on a scaling factor that removes explicit dependence to noise variance and on a reduced diagonal matrix that is derived from a diagonal matrix that is, in turn, derived from a matrix that is dependent on an overcomplete transform set applied in obtaining each $\hat{x}(n)$.
- 13. An apparatus for obtaining an estimate of a noise-free portion of a noise-containing digital signal, the apparatus comprising:

one or more components configured to:

apply a set of M linear transforms to the noise-containing digital signal;

determine M initial de-noised estimates of each digital element of the digital signal;

derive a combination of weight factors for the M initial de-noised estimates of each digital element by formulating the combination as a linear estimation problem and solving it for the individual weight factors; and

formulate a final de-noised estimate of each digital element based on the corresponding M initial de-noised estimates and the combination of weight factors determined in steps (b) and (c) respectively.

- 20 14. The apparatus of claim 13, wherein the set of *M* linear transforms is applied to the digital signal as a whole or to each digital element.
 - 15. The apparatus of claim 13, wherein, for each linear transform in the set of M linear transforms, the M initial de-noised estimates of a particular digital element are obtained by thresholding each transform coefficient that has an absolute value below a threshold and inverse transforming the non-thresholded transform coefficients.

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- 16. The apparatus of claim 13, wherein the combination of weight factors is an optimal combination.
- 17. The apparatus of claim 13, wherein the combination of weight factors is derived such that a conditional mean squared error with respect to the initial denoised estimates is minimized.
- 18. The apparatus of claim 13, wherein the set of *M* linear transforms comprises (i) a discrete cosine transform and a predetermined number of its overcomplete shifts, (ii) a wavelet transform and a predetermined number of its overcomplete shifts, or (iii) a Fourier transform and a predetermined number of its overcomplete shifts.
- 19. The apparatus of claim 13, wherein the digital signal is an image or video frame comprised of a plurality of pixels, wherein each digital element comprises one or a group of pixels.
- 20. A device-readable medium having a program of instructions for directing a
 15 machine to perform a process of obtaining an estimate of a noise-free portion of a noise-containing digital signal, the program comprising:
 - (a) instructions for applying a set of M linear transforms to the noise-containing digital signal;
- (b) instructions for determining *M* initial de-noised estimates of each digital element of the digital signal;
 - (c) instructions for deriving a combination of weight factors for the M initial de-noised estimates of each digital element by formulating the combination as a linear estimation problem and solving it for the individual weight factors; and
- (d) instructions for formulating a final de-noised estimate of each digital element based on the corresponding M initial de-noised estimates and the combination of weight factors determined in steps (b) and (c) respectively.

- 21. The device-readable medium of claim 20, wherein instruction (a) comprises instructions for applying the set of M linear transforms to the digital signal as a whole or to each digital element.
- 22. The device-readable medium of claim 20, wherein instruction (b) comprise instructions for obtaining the *M* initial de-noised estimates of each digital element by thresholding each transform coefficient, of each linear transform in the set of M linear transforms, that has an absolute value below a threshold and inverse transforming the non-thresholded transform coefficients.
- 23. The device-readable medium of claim 20, wherein, in instruction (c), the combination of weight factors is an optimal combination.
 - 24. The device-readable medium of claim 20, wherein, in instruction (c), the combination of weight factors is derived such that a conditional mean squared error with respect to the initial de-noised estimates is minimized.
- 25. The device-readable medium of claim 20, wherein, in instruction (a), the set of *M* linear transforms comprises (i) a discrete cosine transform and a predetermined number of its overcomplete shifts, (ii) a wavelet transform and a predetermined number of its overcomplete shifts, or (iii) a Fourier transform and a predetermined number of its overcomplete shifts.
- 26. The device-readable medium of claim 20, wherein the digital signal is an image or video frame comprised of a plurality of pixels, wherein each digital element comprises one or a group of pixels.
 - 27. A device-readable medium having a program of instructions for directing a machine to perform a process of obtaining an estimate \hat{x} of a noise-free portion x of a noise-containing signal y, the program comprising:
- 25 instructions for obtaining an estimate $\hat{x}(n)$ for each element n of \hat{x} according to the following equation:

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$$\hat{x}(n) = \sum_{i=1}^{M} \alpha_i(n) \hat{x}_i(n), n = 1,...,N$$

wherein weight factors $\alpha_i(n)$, i=1,...,M, n=1,...,N are optimally determined by formulating a combination thereof as a linear estimation problem; and

instructions for combining the N $\hat{x}(n)$ estimates to obtain \hat{x} .

- 28. The device-readable medium of claim 27, wherein $\alpha_i(n)$ are optimally determined such that $\hat{x}(n)$ minimizes a conditional mean squared error with respect to the initial de-noised estimates.
- 29. The device-readable medium of claim 28, wherein $\alpha_i(n)$ are optimally determined based on a scaling factor that removes explicit dependence to noise variance and on a matrix that is dependent on an overcomplete transform set applied in obtaining each $\hat{x}(n)$.
 - 30. The device-readable medium of claim 28, wherein $\alpha_i(n)$ are optimally determined based on a scaling factor that removes explicit dependence to noise variance and on a diagonal matrix that is derived from a matrix that is dependent on an overcomplete transform set applied in obtaining each $\hat{x}(n)$.
 - 31. The device-readable medium of claim 28, $\alpha_i(n)$ are optimally determined based on a scaling factor that removes explicit dependence to noise variance and on a reduced diagonal matrix that is derived from a diagonal matrix that is, in turn, derived from a matrix that is dependent on an overcomplete transform set applied in obtaining each $\hat{x}(n)$.